1. User selects Calibrate Sensors option
2. System presents calibration menu
3. User selects Accelerometer
4. System presents accelerometer calibration menu, containing an inertial graph
5. User sets the zero position button once the RC is stable
   1. System notifies SensorStreamController to send the sendAccelerometerOffset
6. System sends zero signal to accelerometer
   1. SensorStreamManager sends the signal to the ServerControlManager
   2. ServerControlManager sends the signal to the ServerManager on the Jetson board
   3. SensorMonitor uses the vector offset to calibrate the readings from the accelerometer
   4. SensorMonitor sends the readyUpdateSensor signal
   5. ServerManager invokes the sendSensorPacket slot
   6. SensorStreamManager receives the packet and invokes processSensorData
7. System displays success dialog and shows inertial graph with a “zeroed” position